SERVOS

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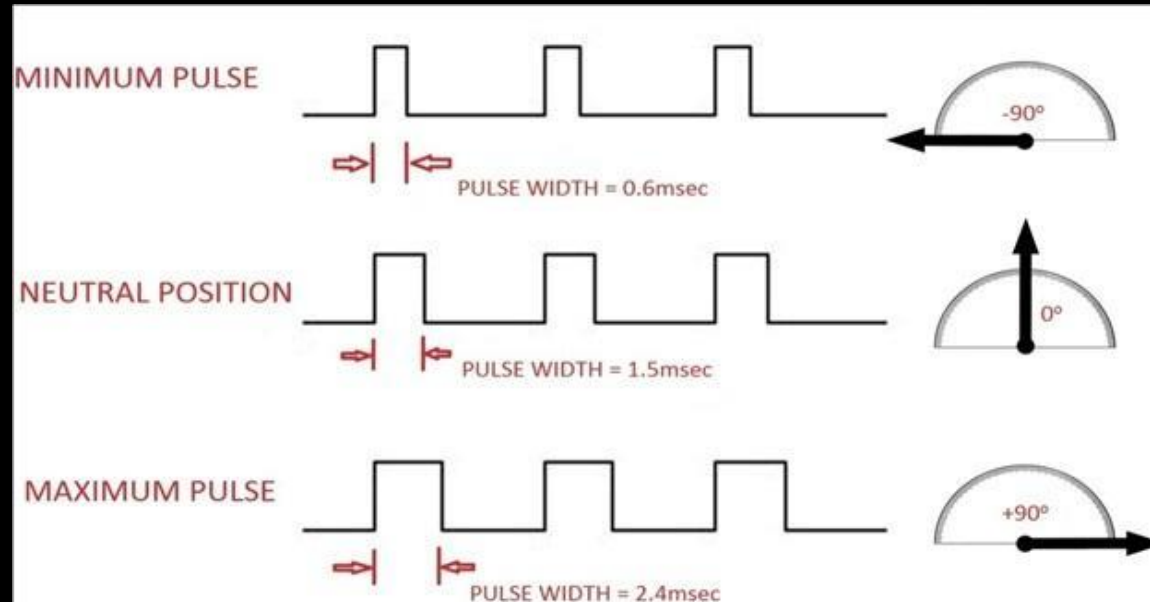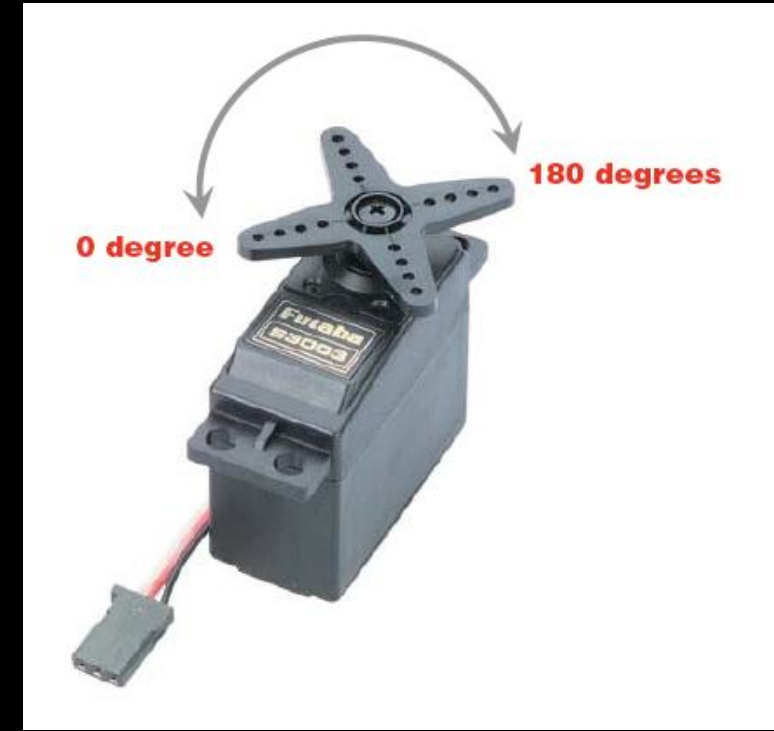
New Words...

- Servo
- 360 Servo
- PWM – Pulse Width Modulation
- Position

MOVE A SERVO MOTOR
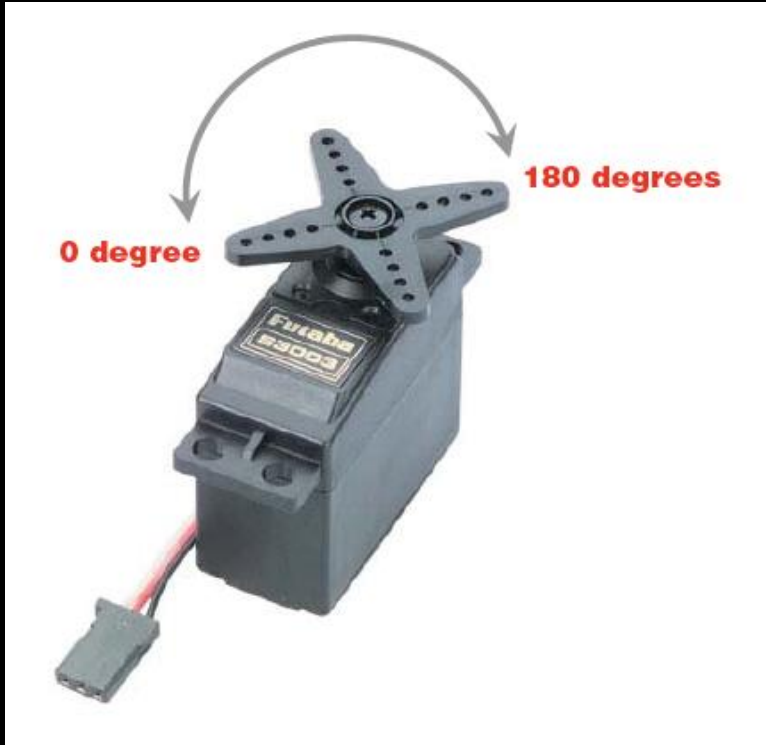

- PWM?
  - Pulse Width Modulation
- Lets Watch a <u>Servo Motor Video</u>

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WRITING TO A SERVO MOTOR

0 degree — 180 degrees

```
#include <Servo.h>
Servo fingerServo;  // create servo object to control a servo
// ---------------------------------------------------------------------------------
// the setup function runs once when you press reset or power the board
void setup() {
  fingerServo.attach(9);  // attaches the servo on pin 8 to the servo object
  //Setting Servos to a default position
  fingerServo.write(20);
}
// ---------------------------------------------------------------------------------
// the loop function runs over and over again forever
void loop()
{
  fingerServo.write(20);
  delay(2000);
  fingerServo.write(80);
  delay(2000) ;
}
```

Github - servo_1_STEAMClown

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360 Servo
Really is a Variable Speed Gear Motor

- Stop - To have a 360 motor stop, set the position around 90

- Forward - set the position around 0

- Backwards - set the position around 180? 360?

#define STOP_L 95
#define STOP_R 95

#define FWD_L 0
#define FWD_R 360

#define BWD_L 180
#define BWD_R 0

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REFERENCE SLIDES

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APPENDIX

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